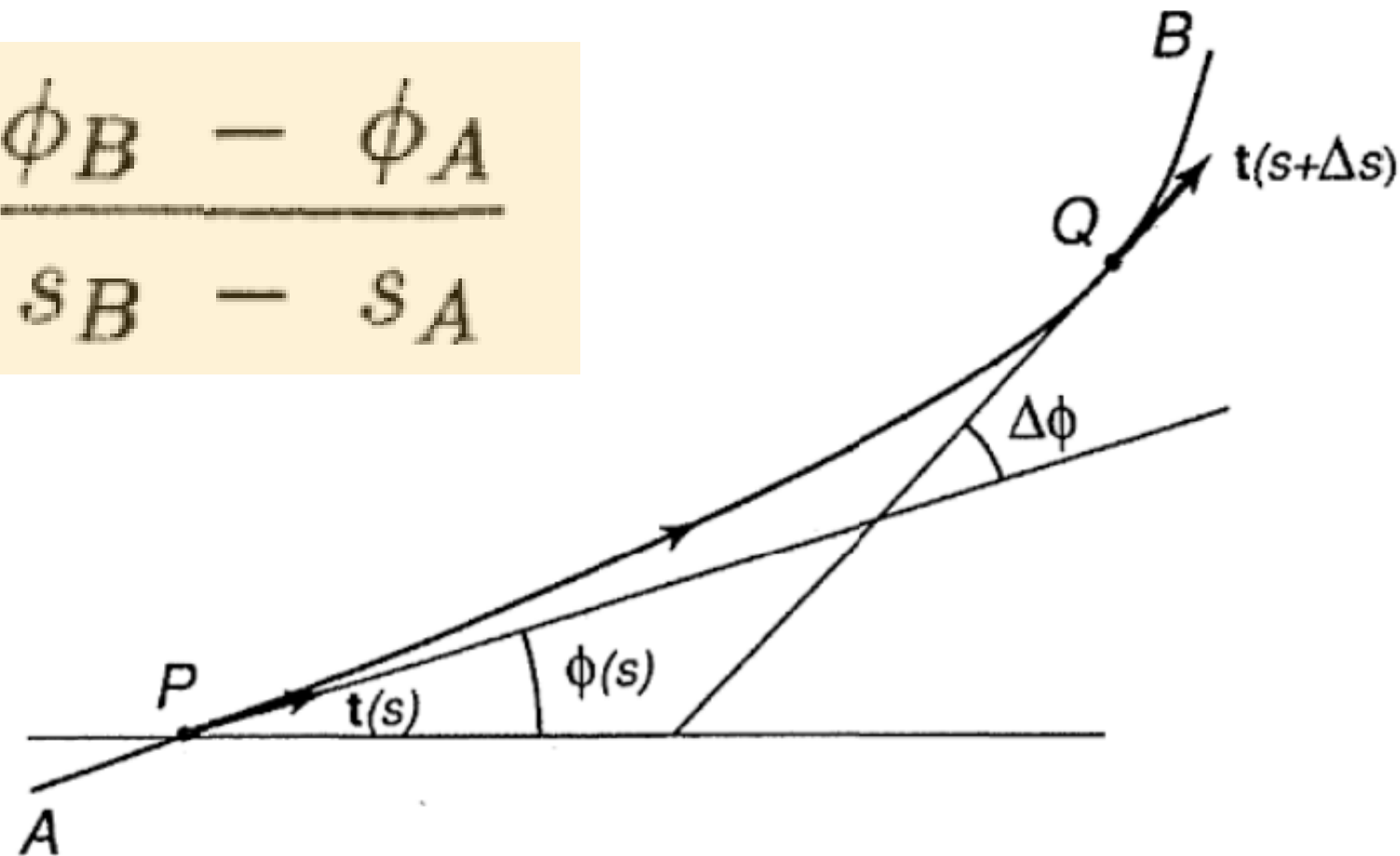


James Casey

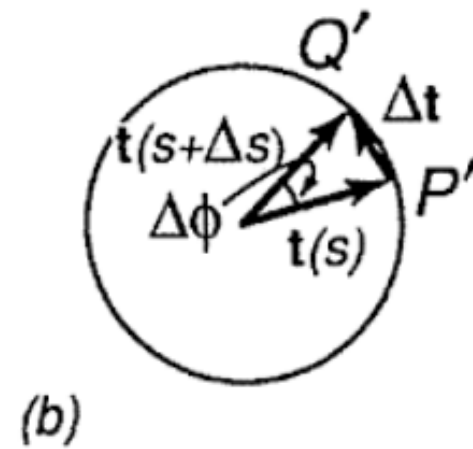
Exploring Curvature

With 141 Illustrations

$$\kappa_{avg} = \frac{\phi_B - \phi_A}{s_B - s_A}$$



(a)



(b)

it is the quotient of the length of the arc $P'Q'$ on the auxiliary circle and the length of the arc PQ on the curve whose curvature is being investigated.

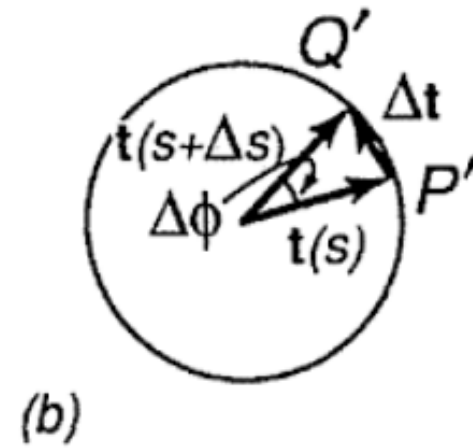
Remark 2 . The total curvature of an arc AB can be written in terms of the curvature κ as an integral, namely

$$\phi_B - \phi_A = \int_{s_A}^{s_B} \frac{d\phi}{ds} ds = \int_{s_A}^{s_B} \kappa ds \quad , \quad (10.9)$$

where s_A and s_B are the values of the arc lengths at A and B . For this reason, the total curvature is also referred to as the *integral curvature* of an arc.

$$\frac{d\mathbf{t}}{ds} = \lim_{\Delta s \rightarrow 0} \frac{\mathbf{t}(s + \Delta s) - \mathbf{t}(s)}{\Delta s} . \quad (10.10)$$

The quantity $\mathbf{t}(s + \Delta s) - \mathbf{t}(s)$ is the change in the unit tangent vector as one goes from P to Q and is represented by the vector $\Delta\mathbf{t}$ joining P' to Q' on the auxiliary circle in Fig. 68b. The derivative $d\mathbf{t}/ds$ is therefore a measure of the rate at which the unit tangent vector changes its direction as one moves along the curve.

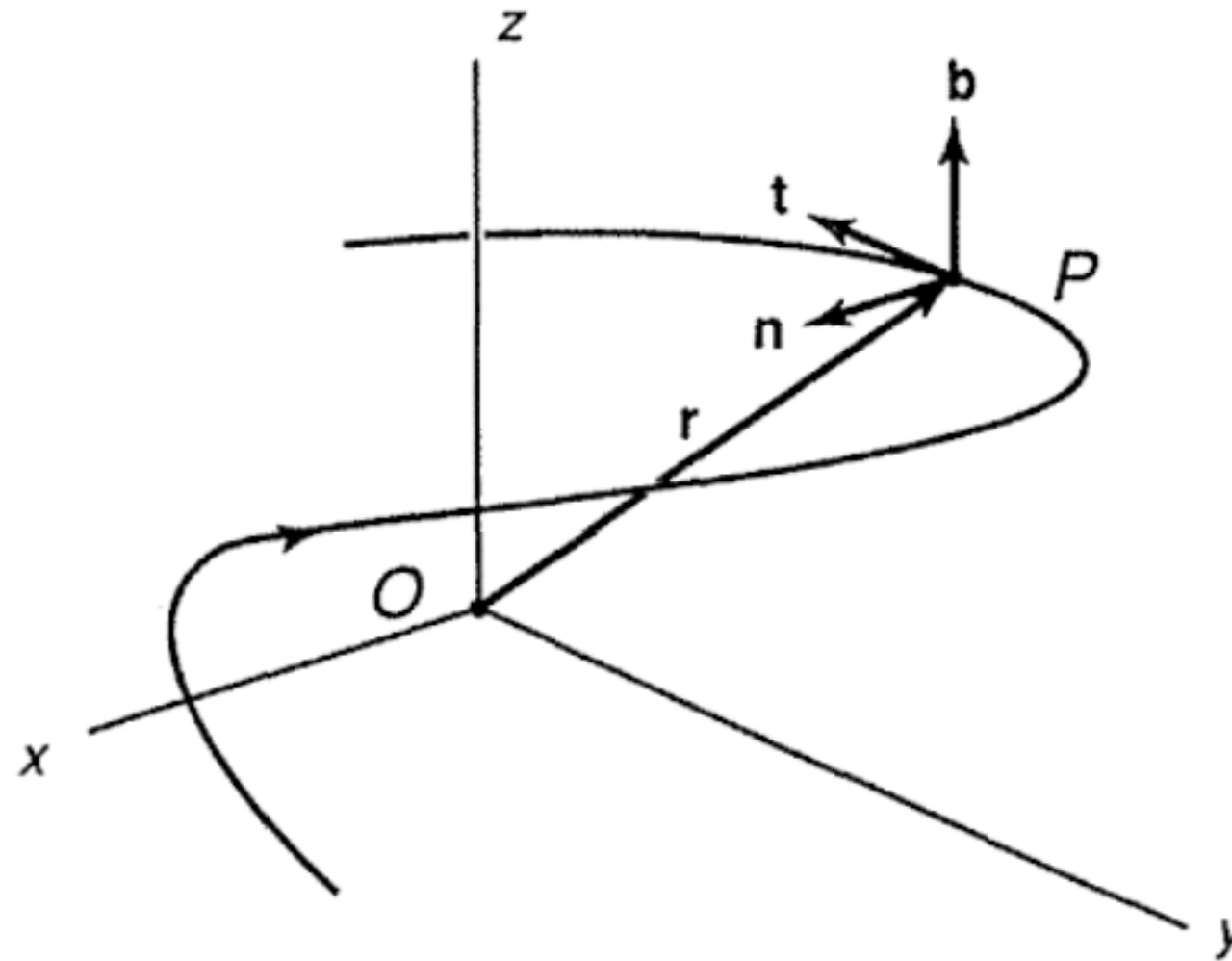


$$\frac{d\mathbf{t}}{ds} = \lim_{\Delta s \rightarrow 0} \left(\frac{\Delta \mathbf{t}}{\Delta \phi} \frac{\Delta \phi}{\Delta s} \right), \quad (10.11)$$

and making use of Equation (10.3), we will arrive at the expression

$$\frac{d\mathbf{t}}{ds} = \kappa \mathbf{n}. \quad (10.12)$$

We may now think of \mathbf{n} as a unit vector which is perpendicular, or *normal*, to the tangent to the curve AB at P in Fig. 68a. It is called the *principal unit normal vector*. The vector $d\mathbf{t}/ds$ is called the *curvature vector* (and is often denoted by a separate symbol). Equation (10.12) has



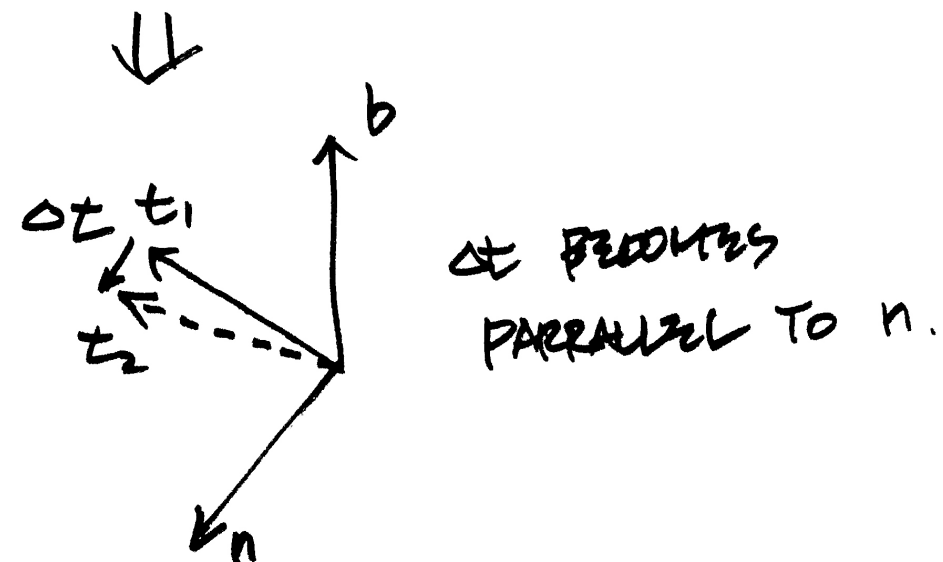
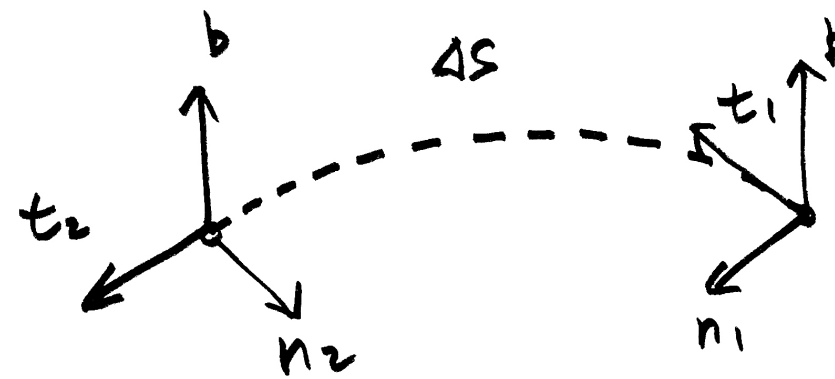
unit normal vector \mathbf{n} . The plane of \mathbf{t} and \mathbf{n} , called the *osculating plane*, is no longer a fixed plane, but instead, rotates as we move along the curve. Let \mathbf{b} be a unit vector perpendicular to the osculating plane, drawn as shown in Fig. 80. This vector is called the *unit binormal vector*. So, at each point along the curve, we now have a triad of unit vectors, \mathbf{t} , \mathbf{n} , \mathbf{b} , making right-angles with one another.

$$\begin{aligned}
 \frac{d\mathbf{t}}{ds} &= \kappa \mathbf{n} , \\
 \frac{d\mathbf{n}}{ds} &= -\kappa \mathbf{t} + \tau \mathbf{b} , \\
 \frac{d\mathbf{b}}{ds} &= -\tau \mathbf{n} .
 \end{aligned}
 \tag{10.13}$$

The first of these we have met before as Equation (10.12): it states that the rate at which \mathbf{t} is changing with respect to arc length s is equal to the curvature κ times the principal unit normal \mathbf{n} . The last formula of the three shows that the rate at which the binormal \mathbf{b} is changing can be expressed as a real number τ , called the *torsion*, times the unit vector $-\mathbf{n}$. Since \mathbf{b} is perpendicular to the osculating plane, this equation implies that for $\tau \neq 0$ the normal to the osculating plane turns in the direction opposite to the unit vector \mathbf{n} . For a plane curve, both $d\mathbf{b}/ds$ and the torsion vanish. The second formula in the set describes how the principal normal is changing as a function of arc length: it has two components—one points opposite to \mathbf{t} , and the other points along \mathbf{n} . The Serret-Frenet formulae are the main tool for the analytical study of

$$\frac{d\mathbf{t}}{ds} = \kappa \mathbf{n} ,$$

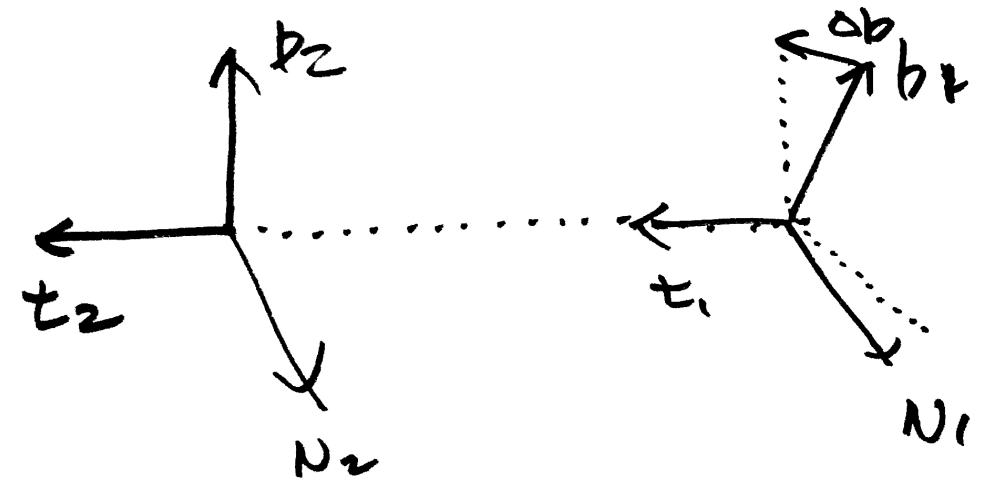
WHEN κ IS CONSTANT (NOT CHANGING) I.E.
IN PLANAR CURVE.



Source: <https://www.khanacademy.org/multivariable-calculus/multivariable-derivatives/derivatives-of-vector-valued-functions/a/multivariable-calculus-derivatives-of-vector-valued-functions-1/a/multivariable-calculus-derivatives-of-vector-valued-functions-1>

$$\frac{d\mathbf{b}}{ds} = -\tau \mathbf{n}.$$

WHEN τ IS CONSTANT / NOT CHANGING
 (IS NOT POSSIBLE THEORETICALLY THOUGH,)
 → IMAGINE TWISTING WIRE?



→ $\Delta \mathbf{b}$ BECOMES
 PARALLEL TO \mathbf{n} .

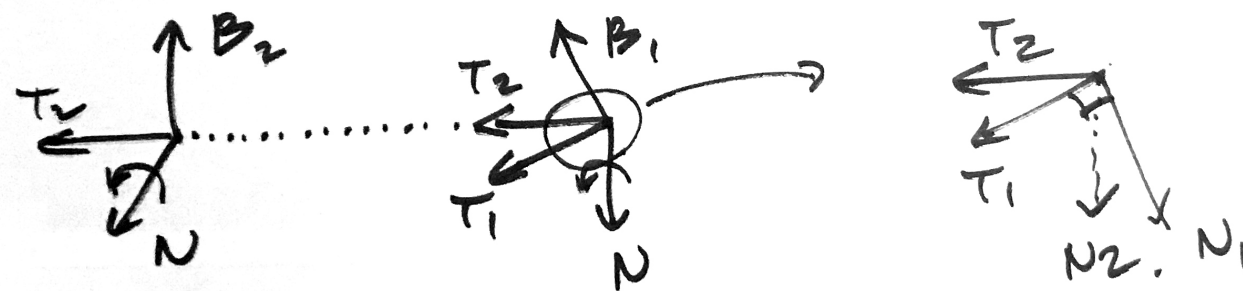
IF N IS CONSTANT / NOT CHANGING

→ TWO OTHER VECTORS ROTATE ALONG N VECTOR

AS THE POINT ON A CURVE TRAVELS ALONG THE CURVE

→ T VECTOR WILL CHANGE → THEN ' N ' IS NOT CONSTANT?

→ OR, ' N ' CHANGES IT'S POSITION.



$$\frac{d\mathbf{t}}{ds} = \kappa \mathbf{n} ,$$

$$\frac{d\mathbf{n}}{ds} = -\kappa \mathbf{t} + \tau \mathbf{b} , \quad (10.13)$$

$$\frac{d\mathbf{b}}{ds} = -\tau \mathbf{n} .$$